

Distribution of Consensus in a Broadcasting-based Consensus-forming Algorithm

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- 2 Formulation of the Problem
- 3 Fundamental Equations for the Consensus
- 4 Consensus of Two Agents
- 5 Consensus of an Infinite Number of Agents
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Background and Motivation

- In a **consensus-forming** algorithm [1], agents initially having different opinions mutually exchange and thereby update their opinions to achieve a consensus.
- In a **broadcasting-based consensus-forming algorithm** [2], at each discrete time, one agent is chosen randomly to broadcast its opinion to neighbors. Agents receiving an opinion **compute the weighted average of their opinions and the received one**.
- It is proved that the opinions of the agents almost surely converge to a consensus, but **little is known about the statistical properties of the achieved consensus**.

[1] M. H. DeGroot, "Reaching a consensus," Journal of the American Statistical Association, vol. 69, issue. 345, 1974.

[2] T.C. Aysal, M.E. Yildiz, A.D. Sarwate, and A. Scaglione, "Broadcast gossip algorithms for consensus," IEEE Transactions on Signal processing vol. 57, no. 7, 2009.

Purpose

- To investigate the **statistical properties of the consensus** in a broadcasting-based consensus-forming algorithm.
- For this purpose,
 - fundamental equations (fixed-point equations) concerning the consensus achieved in the algorithm are derived.
 - based on the derived equations, two extreme cases (consensus forming **by two agents** and consensus forming **by an infinite number of agents**) are investigated.

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Formulation of the Problem

- N agents interact over a directed graph with adjacency matrix $A = \{a_{ij}\}$.
- At each discrete time, one agent broadcasts its opinion. The probability that agent i broadcasts its opinion at a given time is denoted by $p_i > 0$.
- Opinions of agents at time $n(= 0, 1, 2, \dots)$ is denoted by $\mathbf{x}(n) \stackrel{\text{def}}{=} (x_0(n), \dots, x_{N-1}(n))$, where $x_i(n) \in \mathbb{R}$ is the opinion of agent i .

Formulation of the Problem

- Opinion updating at time n is expressed by

$$\mathbf{x}(n+1)^\top = Q^{(e_n)} \mathbf{x}(n)^\top,$$

where e_n denotes the agent broadcasting its opinion at time n and $Q^{(k)} = \{q_{ij}^{(k)}\}$ is the matrix with the following elements:

$$q_{ij}^{(k)} = \begin{cases} 1 - w_{ki}a_{ki}, & i = j \\ w_{ki}a_{ki}, & i \neq j, j = k \\ 0. & \text{otherwise} \end{cases}$$

- w_{ji} is a parameter indicating the degree to which agent j influences the opinion of agent i .

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Additional Assumptions and Notation

- Assume a mesh and a homogeneous network between agents.

$$\forall i, j \ (i \neq j), \quad w_{ij} = w, \quad a_{ij} = 1.$$

- X denotes the opinion broadcasted at time 0. Its distribution is given by

$$P(X = x_i(0)) = p_i, \quad i = 1, \dots, N.$$

- The consensus is denoted by X_∞ .

Fundamental Equations for the Consensus

Theorem 4.1

X_∞ satisfies the following fixed-point equation:

$$X_\infty \stackrel{d}{=} (1 - w)X_\infty + wX.$$

The first and second terms on the right-hand side are statistically independent.

Theorem 4.2

$$X_\infty \stackrel{d}{=} w \sum_{k=0}^{\infty} (1 - w)^k X_k,$$

where X_0, X_1, \dots are independent random variables and are identically distributed with X .

Outline of the Proof of Theorem 4.1

Consensus X_∞ can be expressed as

$$X_\infty = \pi \left(\prod_{n=0}^{\infty} Q^{(e_n)} \right) \mathbf{x}^\top, \quad \prod_{n=0}^{\infty} Q^{(e_n)} \stackrel{\text{def}}{=} \lim_{m \rightarrow \infty} Q^{(e_m)} \dots Q^{(e_0)}.$$

where $\mathbf{x} \stackrel{\text{def}}{=} \mathbf{x}(0)$ is the initial opinion and π is the eigenvector of $\sum_{k=1}^N p_k Q^{(k)}$. We see

$$Q^{(e_0)} \mathbf{x}^\top = (1-w)\mathbf{x}^\top + w x_{e_0} \mathbf{1}^\top, \quad \left(\prod_{n=1}^{\infty} Q^{(e_n)} \right) \mathbf{1}^\top = \mathbf{1}^\top.$$

Thus,

$$X_\infty = (1-w)\pi \left(\prod_{n=1}^{\infty} Q^{(e_n)} \right) \mathbf{x}^\top + w x_{e_0}.$$

Here, $\pi \left(\prod_{n=1}^{\infty} Q^{(e_n)} \right) \mathbf{x}^\top$ is the consensus reached when the opinions at time 1 are equal to \mathbf{x} , which is equal to X_∞ in distribution, while x_{e_0} is equal to X in distribution. These observations complete the proof.

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Additional Assumption and Notation

- Initial opinion of agent 0 is 0 and initial opinion of agent 1 is 1.
- $p_0 = p_1 = 0.5$ (agents 0 and 1 broadcast their opinions with probability 0.5 at each discrete time.)
- Define the mapping $f_w : [0, 1) \rightarrow [0, 1)$,

$$y = \sum_{k=1}^{\infty} \frac{\epsilon_k(y)}{2^k} \longrightarrow f_w(y) = w \sum_{k=1}^{\infty} (1-w)^{k-1} \epsilon_k(y).$$

Note that f_w is the inverse of the generalized Cantor function when $w > 0.5$.

Properties of $f_w(y)$

- When $w \neq 0.5$, $f_w(y)$ is discontinuous at $y \in \Lambda$ and continuous on $[0, 1) \setminus \Lambda$, where

$$\Lambda \stackrel{\text{def}}{=} \{y_{n,k} : n = 1, 2, \dots, k = 0, 1, \dots, 2^{n-1} - 1\}, \quad y_{n,k} \stackrel{\text{def}}{=} \frac{2k + 1}{2^n}.$$

When $w = 0.5$, $f_w(y) = y$ and thus $f_w(y)$ is continuous on $[0, 1)$.

- When $w \geq 0.5$, $f_w(y)$ is strictly increasing.
- When $w < 0.5$, $f_w(y)$ jumps downward at discontinuous points.

Main Results

Theorem 5.3

$$P(X_\infty \leq x) = \mu_l (f_w^{-1} ([0, x])) ,$$

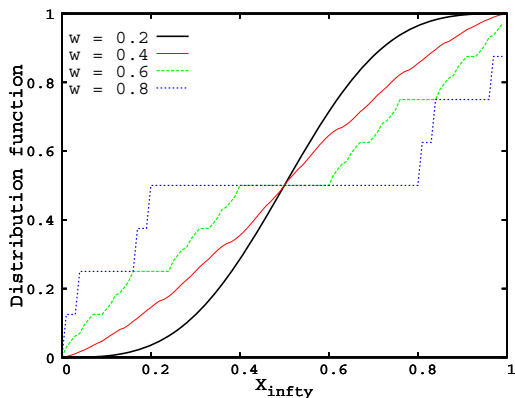
where μ_l denotes the Lebesgue measure.

Theorem 5.4

- If $w \leq 0.5$, then $X_\infty(\Omega) = [0, 1)$ and any $z \in [1, 0)$ could be an outcome of X_∞ .
- If $w > 0.5$, then $\mu_l (X_\infty(\Omega)) = 0$ and the Lebesgue measure of the set of the possible outcomes of X_∞ is zero.

Numerical Examples

- Shape of the distribution function of X_∞ depends greatly on w .



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Assumptions and Definitions

- Assume that X (opinion broadcasted at time 0) is a continuous random variable.
- This assumption corresponds to the case of letting the number of agents go to infinity.

Definition 6.1

Two random variables Z_1 and Z_2 are said to be of the **same type** if there exist constants $a > 0$ and $b \in \mathbb{R}$ with $Z_2 \stackrel{d}{=} aZ_1 + b$.

Definition 6.2

A random variable Z is **stable** if, for any positive constants a and b , $aZ_1 + bZ_2$ is the same type as Z , where Z_1 and Z_2 are independent copies of Z .

Consensus of an Infinite Number of Agents

Theorem 6.3

If X is stable, the consensus X_∞ is of the same type as X .

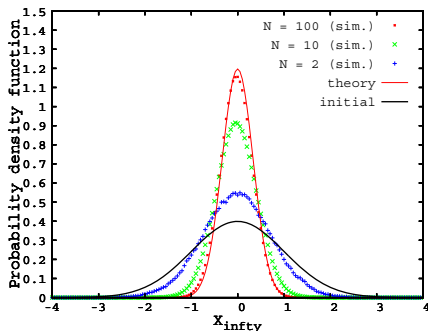
- Outline of the proof.
 - If X is stable, $w \sum_{k=0}^{\infty} (1-w)^k X_k$ is of the same type as X .
 - Thus, applying Theorem 4.2 completes the proof.
- A closed-form expression of the distribution of X_∞ can be derived if X follows a Gaussian, Cauchy, or Lévy distribution.

Case 1: Initial Opinions Follow a Gaussian Dist.

- If X follows a Gaussian distribution with mean μ and variance σ^2 , the consensus also follows a Gaussian distribution with mean μ and variance $\sigma_\infty^2 = \frac{w\sigma^2}{2-w}$, where

$$\lim_{w \rightarrow 0} \sigma_\infty^2 = 0, \quad \lim_{w \rightarrow 1} \sigma_\infty^2 = \sigma^2.$$

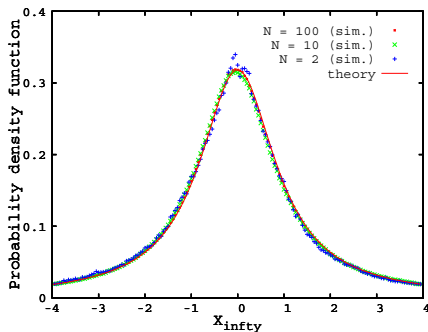
$$w = 0.2$$



Case 2: Initial Opinions Follow a Cauchy Dist.

- If X follows a Cauchy distribution, then the consensus is identically distributed with the initial opinion.

$$w = 0.2$$

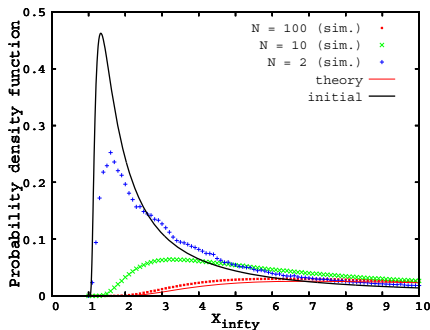


Case 3: Initial Opinions Follow a Lévy Dist.

- If X follows a Lévy distribution with location and scale parameters δ and γ , the consensus also follows a Lévy distribution with location and scale parameters δ and $\gamma_\infty \stackrel{\text{def}}{=} \frac{\gamma w}{2-w-2\sqrt{1-w}}$, where

$$\lim_{w \rightarrow 0} \gamma_\infty = \infty, \quad \lim_{w \rightarrow 1} \gamma_\infty = \gamma.$$

$$w = 0.2$$



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Conclusion

- The statistical properties of the consensus in a broadcasting-based consensus-forming algorithm were investigated.
- In the infinite-number-of-agents case, if the initial opinions follow a stable distribution, then the consensus also follows a stable distribution.
- A closed-form expression for the distribution of the consensus exists if the initial opinions follow a Gaussian, Cauchy, or Lévy distribution.

Thank you very much.